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Relative dispersal ability of a key agricultural pest and its predators in an annual agroecosystem

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HIGHLIGHTS

G R A P H I C A L A B S T R A C T

- Large-scale mark-capture experiments were conducted using protein markers.
- Relative dispersal abilities of an agricultural pest and its predators was measured.
- The dispersal ability of the pest fell near the average dispersal of its predators.
- ► *Lygus* did not escape its predators by out-dispersing them.



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ABSTRACT

In predator–prey interactions, a widely held view is that prey species have higher dispersal rates relative to their predators and are thereby able to escape from predation by colonizing habitats before their predators. Despite major implications for predator–prey interactions, community assembly, and biological control, this view has rarely been tested, and measuring relative dispersal abilities is often complicated by colonizing predators and prey originating from different locations. In California's San Joaquin Valley, the periodic harvest of alfalfa presents an opportunity to measure dispersal of a key generalist pest, *Lygus* spp., relative to a suite of its generalist predators. We performed a large–scale mark-capture study by marking a mature alfalfa field containing *Lygus* and its predators with an aerial application of a protein marker. The alfalfa was then harvested by the grower, prompting a dispersal event. At several times following harvest, surrounding cotton fields were sampled at known distances from the marked field to quantify movement by *Lygus* and its predators. Instead, the mean dispersal distance for *Lygus* fell near the average dispersal distances of its predators. Implications for biological control are discussed in light of these results, and the importance of predators' trophic strategy is stressed.

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1. Introduction

The importance of dispersal in the persistence of predator-prey interactions has long been recognized in the theoretical literature (Holyoak and Lawler, 1996; Kareiva, 1990; Taylor, 1990). Early

models (reviewed in Taylor, 1990) demonstrated that if prey disperse into newly-available habitats without predators, they can escape control. Free of predators and without food limitation, these prey populations experience unrestrained population growth, which is checked only after colonization by predators or the

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depletion of resources. Inherent in these models is the commonly held, but largely untested, assumption that prey have high dispersal rates relative to those of their predators. Differential dispersal has been demonstrated theoretically to be necessary for persistence of predator prey interactions in a metapopulation context (Hauzy et al., 2010; Taylor, 1990). It also underlies early empirical studies of the effects of spatial heterogeneity on predator prey interactions, where habitat patchiness promoted outbreaks of pests (Kareiva, 1987; Roland, 1993).

Despite theoretical evidence that differences in the relative dispersal ability of prey and their predators is important, empirical studies are rare. In terrestrial systems, empirical studies almost exclusively derive from research with insect hosts and their parasitoids (reviewed by Cronin and Reeve, 2005). In natural systems, the movement of parasitoids relative to their hosts (and relative to their competitors) has been investigated to understand patterns of species coexistence (Elzinga et al., 2007; Hopper, 1984; Roland and Taylor, 1997; van Nouhuys and Hanski, 2002). However, because these studies generally do not definitively identify the origins of migrants, movement distances cannot be directly quantified. Additionally, as noted by Cronin and Reeve (2005), these studies assess parasitoid movement using observations of the distribution of parasitized hosts. Parasitoids that disperse beyond the distribution of their dispersing hosts are not observed, and parasitoid dispersal ability may be underestimated using this method (Darrouzet-Nardi et al., 2006).

In aquatic systems, the dispersal of predators and their prey have been examined empirically on a landscape-scale to understand the drivers of community assembly (Hein and Gillooly, 2011; Shulman and Chase, 2007). These studies have demonstrated the importance of both dispersal and resource limitation in community assembly. Hein and Gillooly (2011) found that both predators and prey were dispersal limited, but did not explicitly state whether prey species out-dispersed predator species (or visaversa). They also highlighted that the importance of dispersal limitation can change over time, suggesting that it is important to consider the transient state of these systems.

In annual agroecosystems, frequent disturbances create a system of patches continually in a transient state. Over the course of a growing season, annual crops change in their availability and suitability, necessitating frequent colonization and recolonization by pests and their predators (Wiedenmann and Smith, 1997; Wissinger, 1997). In such systems, early colonization of new crops by predators has been demonstrated both theoretically (Bianchi et al., 2009; Ives and Settle, 1997) and empirically (Landis and van der Werf, 1997; Settle et al., 1996) to be a key feature in their ability to suppress pest populations. As in early predator-prey models, these studies make the key assumption that pests have already colonized the patch; the early colonization by predators merely reduces the time lag between pest establishment and predator colonization (but see Settle et al., 1996). In these studies, predators and prey are not necessarily assumed to be emigrating from the same source (Bianchi et al., 2010, 2009) and dispersal events may not occur at the same time. Thus, it remains unclear how the relative dispersal abilities of predators and their prey affect their colonization abilities and subsequent interactions.

The periodic hay harvest of alfalfa (*Medicago sativa* L.) presents an opportunity to simultaneously study movement of a community of arthropods (Hossain et al., 2000; Pearce and Zalucki, 2005; Schaber et al., 1990), including plant bugs in the genus *Lygus* (Hemiptera: Miridae), which are important agricultural pests, and their suite of predators. Several species of *Lygus* often co-occur in California's San Joaquin Valley and are managed the same way in terms of agricultural systems. Thus, in this study we will refer to a combination of *Lygus hesperus* Knight and *Lygus elisus* Van Duzee simply as '*Lygus*' (See Supplementary Data Appendix A for species' frequencies for species' frequencies). *Lygus* feeds on a broad array of crops grown in California's San Joaquin Valley and displays a preference for several common crops, including alfalfa. Alfalfa is a perennial crop and a preferred host, and *Lygus* is thought to overwinter in alfalfa or colonize alfalfa fields early in the growing season. Large populations build up in alfalfa, peaking by the late spring (Sevacherian and Stern, 1975). The monthly harvest of alfalfa is thought to displace *Lygus*, and emigrants may serve as a major source of *Lygus* colonists for young cotton (*Gosspium hirsutum* L.) plantings. In cotton *Lygus* are major pests and can cause economic damage even at low densities (Rosenheim et al., 2006).

In addition to harboring *Lygus*, alfalfa typically contains a rich community of predators (Hossain et al., 2000), including several generalist insect predators that are potential control agents for *Lygus*, including damsel bugs (*Nabis* spp.; Perkins and Watson, 1972), big-eyed bugs (*Geocoris* spp.), and lacewings (*Chrysoperla* spp.; Hagler, 2011). Despite this suite of predators, the biological control of *Lygus* in most crops appears to be relatively weak. An understanding of the relative dispersal ability of *Lygus* and its predators may provide insight into the biological control of this important pest. If *Lygus*' dispersal ability is high relative to its predators, then one possible mechanism explaining why this pest is under poor control is that it escapes its predators in space.

Until recently, it has been technically difficult to estimate the relative dispersal abilities of pests and their predators on a scale relevant to crop colonization. Movement of populations of small arthropods has traditionally been studied using mark-releaserecapture techniques. In most studies, insects are reared in the lab or collected en masse, marked in the lab, released back into the field at a central location, and then recaptured at known time and distance intervals. The need to mark individual insects limits the size of the population that can be marked, reducing the likelihood of detecting rare long-distance dispersal events. Additionally, as emigrants radiate out from a point source, marked individuals are spread over a progressively larger area as the distance from the release point increases resulting in an area dilution effect. To maintain high capture efficiency and minimize the area dilution effect, most movement experiments have been conducted on relatively small scales. The development of protein markers (Hagler and Jones, 2010; Jones et al., 2006), which are inexpensive and easy to obtain, make it possible to apply markers over a large area in the field with conventional spray equipment, creating a large population of marked individuals. Additionally, this method marks the entire arthropod community within the sprayed area, allowing for the movement of more than one species to be quantified simultaneously.

Using protein marking, we performed a large-scale markcapture experiment to quantify the relative dispersal abilities of *Lygus*, an economically important pest in cotton, and its key predators. We marked alfalfa fields and studied the movement of *Lygus* and its predators following the monthly hay harvest of the alfalfa. These dispersal events likely represent a common situation in the agricultural landscape, where a high-quality habitat becomes rapidly unsuitable and acts as a source of colonists to suitable habitats in the surrounding landscape.

2. Materials and methods

2.1. Study system

Experiments were conducted on three commercial farms in California's San Joaquin Valley: (i) at Buttonwillow Land and Cattle (35°25′31.79″N and 119°24′42.08″W) in May 2006; (ii) at J.G. Boswell Company (35°56′4.75″N and 119°34′23.90″W) in June 2007; and (iii) at Bowles Farming Company (37°7′32.51″N and 120°45′7.58″W) in June 2008. We will first describe elements common to all experiments (Sections 2.2 and 2.3), and then provide details specific to each experiment (Section 2.4). Each site consisted of an alfalfa field adjacent to a continuous stretch of young cotton. To minimize the complicating effects of habitat type on movement rates (Ovaskainen, 2004), we only measured colonization into continuous stretches of cotton fields. Cotton is an annual crop and does not support a community of overwintering insects, so the density of Lygus builds over the cotton growing season. Conversely, the Lygus population in alfalfa, a perennial crop, is more stable over the year. We conducted this study early in the cotton growing season, when cotton was beginning to produce flower buds and become a suitable host for *Lygus* but the resident community was still small, to increase the prevalence of marked individuals in our samples. The likelihood that a sample included marked individuals was higher early in the growing season, as Lygus that leave alfalfa were dispersing into a small recipient *Lygus* population.

2.2. Mark-capture method

To describe the movement of Lygus and its predators resulting from the harvest of alfalfa, we conducted large-scale mark-capture studies using protein marking (Hagler, 1997; Jones et al., 2006). Insect communities in commercial alfalfa fields were marked in the field using crude food proteins: bovine casein (applied as cow's milk; Kirkland Signature, Seattle, WA) or chicken egg albumin (as chicken egg whites; Egg Starts[®], Kirkland Signature, Seattle, WA). Marks were applied aerially by a crop duster. The efficacy of these markers in field applications has previously been confirmed (Hagler and Jones, 2010), and was evaluated here by testing individuals collected from the marked alfalfa field (Table 1). Within 24 h of marking, the alfalfa field was harvested by the grower, prompting a dispersal event. Surrounding cotton fields were sampled for marked insects at fixed distances measured from the edge of the harvested alfalfa field 1 day after harvest, and this sampling was repeated at least once on a later day. Collected insects were sorted in the lab, and adult L. hesperus, L. elisus, Geocoris spp., Chrysoperla carnea spp. (Stephens), Hippodamia convergens Guérin-Méneville, and Nabis spp. were identified and sexed (for relative abundance see Table 2). 'Nabis' consisted of Nabis alternatus Parshley (most common in this system) and Nabis americoferus Carayon (much less common). C. carnea spp. is a complex of species whose systematics remain unresolved (M. Tauber and K. Tauber, Personal communication). Geocoris spp. is a combination of Geocoris pallens Stål and Geocoris punctipes (Say).

2.3. Detecting marked individuals

Collected insects were analyzed for the presence of both egg albumin protein and milk casein protein using protein-specific enzyme-linked immunosorbent assays (ELISA) described by Hagler

Table 1

Marking efficiency of the milk and egg marks for the 2007 and 2008 experiments, measured as the proportion of marked individuals collected from the marked alfalfa field before it was harvested. In 2007, only the egg mark was used. No marking efficiency data were collected for the 2006 experiment.

Year	Species	Egg	Milk
2007	Geocoris spp.	0.61 (11 of 18)	N/A
	Hippodamia convergens	0.65 (17 of 26)	N/A
	Lygus spp.	0.76 (38 of 50)	N/A
	Nabis spp.	1.00 (24 of 24)	N/A
2008	Chrysoperla carnea spp.	1.00 (6 of 6)	0.67 (4 of 6)
	Geocoris spp.	0.32 (48 of 152)	0.15 (23 of 152)
	Hippodamia convergens	1.00 (39 of 39)	0.72 (28 of 39)
	Lygus spp.	0.97 (154 of 159)	0.41 (65 of 159)
	Nabis spp.	1.00 (24 of 24)	0.83 (20 of 24)

and Jones (2010). The amount of protein detected by the ELISA is reported as a continuous optical density (OD) score, and a threshold must be chosen to classify individuals as marked or unmarked. It is important to choose a threshold that minimizes classification errors that can create erroneous patterns in the data set, by first characterizing the distribution of OD scores for the unmarked and marked populations. False positives (unmarked individuals misclassified as marked) are especially problematic in dispersal studies, where they can inflate estimates of long-distance dispersal (Sivakoff et al., 2011). To estimate the distribution of OD scores, we collected control individuals from both the alfalfa and cotton fields before the mark was applied, and then used the control OD scores to estimate the distribution of the unmarked population. We collected individuals from the alfalfa field after it was sprayed with the protein mark, but before the field was cut to establish the distribution of OD scores for the marked population. We characterized the OD distributions separately for each of our focal species. Following Sivakoff et al. (2011) we set a threshold for each species that was associated with a very low (approximately 1 in 1000) false positive rate. Individuals were classified as marked or unmarked using the chosen threshold, and the number of marked individuals was adjusted to account for the false positive rate. For details on the unmarked and marked OD distributions, chosen thresholds, associated false positive rates, and method of correcting for false positives, see Appendix B. To determine the extent of aerial drift of the applied marking solution, we also collected samples from cotton fields surrounding the sprayed alfalfa field after we applied the protein marker solution but before the sprayed field was harvested.

2.4. Experimental design

2.4.1. Experiment 1

On May 29, 2006, a 29.14 ha flowering alfalfa field was sprayed with a 5% milk solution, applied aerially by a commercial crop duster. Within 24 h of marking, the alfalfa field was harvested by the grower. One day after harvest (May 30, 2006) we sampled contiguous cotton fields to the east of the marked field. Samples were collected at eight distances from the eastern edge of the harvested alfalfa field: 10, 50, 100, 150, 200, 400, 600, and 800 m. Samples were collected using an aerial sweep net along transects that ran parallel to the edge of the harvested field. Sampling was repeated 7 days after harvest on June 5, 2006, with additional samples collected at 1000 and 1200 m from the harvested field. A sample consisted of 200 m of sweeping, and at least ten samples were collected at each distance.

2.4.2. Experiment 2

On May 30, 2007 we sprayed the 16.19 northernmost ha of a 119-ha alfalfa field with a 20% egg white solution. The field was cut by the grower the following day. In this landscape we had a large continuous stretch of cotton to the north of the sprayed field, and samples were collected 1, 5, and 12 days (June 1, 5, and 12) after harvest at 10, 50, 100, 200, 400, 800, 1300, 1600, 2400, 3200, 4000, and 4800 m from the northern edge of the focal alfalfa field. Samples were collected using a handheld vacuum (STIHL[®], Andreas Stihl Ag & Co. KG, Waiblingen, Germany) instead of sweep nets to increase sampling efficiency. On each sampling day, and at each distance, we took 10 samples, with each sample defined as 200 m of suction sampling with the vacuum at full force.

2.4.3. Experiment 3

On June 18, 2008, the insect community in a 5.67 ha section of an 32.78 ha alfalfa field was marked using a solution of 40% cow's milk and 20% chicken egg whites. The sprayed alfalfa field was harvested on June 20, prompting a dispersal event. Surrounding cotton F.S. Sivakoff et al./Biological Control 63 (2012) 296-303

fields to the south and west of the sprayed area were sampled for marked insects at 50, 100, and 200 m and at 50, 100, 200, 500, 800, 1100, 1500, 2000, and 2350 m to the north (upwind of the sprayed area). Samples were collected 1, 3, and 5 days after harvest, and on each day, at each distance, we took 14-60 samples (median = 15). Similar to 2007, samples were collected using a handheld vacuum, with a single sample defined as 200 m of suction sampling with the vacuum at full force. While samples were collected in three cardinal directions, only samples collected to the north of the sprayed areas were used in the analysis, as a result of downwind drift of the protein mark.

2.5. Statistical analysis

The differences in experimental design between the 3 years prompted us to analyze each experiment separately. For each experiment, we performed a randomization test (Resampling stats for excel 2007© statistics.com LLC, Arlington, VA) to determine if species differ in their mean dispersal ability. An analysis of variance (ANOVA) using the original data, where species identity of marked individuals was the treatment and the response variable was the distance traveled by each marked individual was used to estimate an F statistic. The F statistic from this ANOVA was then compared to the distribution of F statistics generated from resampling the data 10,000 times. The number of cases that were greater than or equal to the original *F* statistic were counted. This number was divided by 10,000 to produce an approximate P-value for the randomization test. To explore whether particular pairs of species differed in their mean dispersal distance, we repeated the process with the relevant subset of the observations.

2.6. Mean distance flown

To estimate mean distance traveled for each species, movement estimates were adjusted to correct for the differences in area of the sampled annuli and for the number of samples taken at each distance (e.g. Fletcher, 1974). The total number of marked individuals in the *i*th annulus would then be proportional to the density of marked individuals multiplied by the area of the annulus:

$$\frac{n_i}{m_i}(r_{2i}^2 - r_{1i}^2) \tag{1}$$

where, for the *i*th annulus, r_{1i} is the inner radius and r_{2i} is the outer radius, n_i is the total number of marked individuals, and m_i is the number of samples collected. The relative frequency (i.e. the proportion of the total dispersing marked population in the *i*th annulus) is:

$$f_i = \frac{n_i}{m_i} (r_{2i}^2 - r_{1i}^2) \bigg/ \sum_i \frac{n_i}{m_i} (r_{2i}^2 - r_{1i}^2)$$
(2)

The mean distance flown (MDF) is then estimated:

$$MDF = \sum_{i} \hat{f}_{i} \frac{1}{2} (r_{2i} + r_{1i}) = \sum_{i} f_{i} \bar{r}_{i}$$
(3)

where $\bar{r}_i = 1/2(r_{2i} + r_{1i})$ (4)

Given the likely ability of C. carnea and H. convergens to disperse farther than our furthest sampling location, the measures of mean distance flown are minimum estimates. The correction tends to increase mean dispersal distance estimates, because it weighs more heavily the few individuals that were recaptured at the greatest distances from the alfalfa field, where dispersing individuals are expected to be diluted in space.

2007

Flown (meters) ± SE

Μ

12 24 27

1233 1099 631 1066 213

Mean Distance

Number Marked of

those Collected

Collected Number

Flown (meters) ± SE

na 3158 ± 301

na 4516 ± 421

na

na 20 0 7

na* 1257 409 198 409

na 774 ± 56 684 ± 107 na na

na 57 6 1

213 32 48

Hippodamia convergens Chrysoperla carnea spp.

Lygus spp. Nabis spp.

Geocoris spp.

Mean Distance

Number Marked of

those Collected

Collected Number

Flown (meters) ± SE Mean Distance

of those Collected Number Marked

Collected Number 2006

Species

na* 2600

2008

a;

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Fig. 1. Box plot displaying differences in species' movement in the (A) 2006, (B) 2007, and (C) 2008 experiments. The whiskers on the box plot indicate the quantiles. The box with the crosshatching indicates *Lygus*, the pest species. The other species are predators.

3. Results

Positive control samples confirmed the field efficacy of the milk and egg marks, although marking efficiency varied across years and target insect (Table 1). Experiments conducted in 2006 and 2007 generated dispersal estimates for some of the predator species. In 2006, we collected marked individuals of the predators *Geocoris* spp. (captures ranged from 10 to 1200 m, Appendix C) and *H. convergens* (captures ranged from 10 to 800 m, Appendix C), in addition to a single marked *Lygus* that was collected 800 m away from the edge of the marked alfalfa field. The randomization test (using the predators) indicated that there was no significant difference in the mean dispersal distances between these predators (P = 0.13; Fig. 1A). In 2007 we collected marked individuals of the predators *Geocoris* spp. (captures ranged from 10 to 4800 m, Appendix C) and *Nabis* spp. (captures ranged from 10 to 4800 m, Appendix C). As in 2006, the randomization test for the 2007 data indicated that there was no significant difference in the mean dispersal distances between these predators.

Only the 2008 experiment provided data to allow a direct comparison between Lygus movement and that of its natural enemies, it appears that Lygus' mean dispersal distance falls between those of its predators (captures ranged from 50 to 2350 m, Fig. 1C, Table 2). In 2008, there were insufficient captures of marked individuals of Geocoris spp. (number marked = 2, captured at 50 and 1500 m), and these data were excluded from further analysis. The randomization test indicated that there was a significant difference in the dispersal distances across all species (P < 0.001). Pairwise contrasts revealed that on average H. convergens dispersed significantly shorter distances (captures ranged from 50 to 1500 m) than Lygus (P = 0.034), Nabis (P = 0.0011), and C. carnea (*P* = 0.0004). *Nabis* (captures ranged from 100 to 2350 m) and *C*. carnea (captures ranged from 800 to 2350 m) dispersed significantly farther than Lygus (P = 0.017 and P = 0.002, respectively), and there was no significant difference between the mean dispersal distance for Nabis and C. carnea (P = 0.41). Raw dispersal data for all marked individuals can be found in Appendix C.

Dispersal estimates using MDF were inconsistent between years for *Geocoris* and *Nabis* (Table 2). *H. convergens* mean dispersal estimates were similarly low in both 2006 and 2008 ($684 \pm 107 \text{ m}$ vs. $1037 \pm 177 \text{ m}$, respectively) compared to the other arthropods tested, whereas *Geocoris* dispersal estimates were quite different across years ($774 \pm 56 \text{ m}$ vs. $3158 \pm 301 \text{ m}$, respectively). This difference may be due to the very different lengths of the recapture transects for 2006 (1200 m) versus 2007 (4800 m). When the 2007 distances were limited to samples within 1300 m (the closest transect distance to 1200 m), the MDF for *Geocoris* was $1208 \pm 83 \text{ m}$. *Nabis* movement estimates were also quite different in 2007 versus 2008 (4516 m vs. 1637 m, respectively), but the 2007 estimate was heavily influenced by a single long-distance movement event (Fig. 1B).

4. Discussion

The results from the mark-capture experiment demonstrate differences in the average distances Lygus and its predators dispersed. Recaptures of marked individuals moving from alfalfa into cotton suggest that Lygus does not out-disperse its suite of generalist predators. Lygus had an intermediate mean dispersal distance compared to its complex of generalist predators. In 2008, Lygus' mean dispersal was estimated to be greater than that for H. convergens but less than that for Nabis or C. carnea. Of the predators included in this study, Geocoris and Nabis are thought to be effective predators on eggs and early instars of Lygus (Hagler, 2011; Leigh and Gonzalez, 1976; Zink and Rosenheim, 2008). C. carnea and H. convergens will feed on Lygus nymphs in experimental settings (Hagler, 2011), but are not generally thought to be important predators of Lygus (Leigh and Gonzalez, 1976). While direct comparisons with Geocoris are not possible, comparing means dispersal distance across experiments suggests that Lygus does not disperse farther than either of its two main predators, Geocoris and *Nabis.* Our results suggest that the reason why *Lygus* is not effectively controlled by its predators is not because it out-disperses them.

The large majority of studies examining the relative dispersal of insects have focused on the movement of parasitoids and their hosts (e.g. references in Cronin and Reeve, 2005; Elzinga et al., 2007). As discussed by Darrouzet-Nardi et al. (2006), a key challenge to interpreting these studies, which infer parasitoid movement through patterns of host parasitism, is that parasitoid movement cannot be ascertained without the host having first moved to the recapture site. Thus, these studies may underestimate the extent to which natural enemies are capable of dispersing farther than their hosts. A few studies do suggest that parasitoids may often be more mobile than their hosts. Darrouzet-Nardi et al. (2006) found the mean dispersal distance of the parasitoid Platygaster californica to be 4.5 m, while an earlier study estimated the average distance travelled by their female midge host, Rhopalomyia californica, to be 1.7 m (Briggs and Latto, 2000). Jones et al. (1996) performed a mark-release-recapture study of a tephritid fly, Terellia ruficauda, and four of its parasitoids. In that study, dispersal was measured directly using recaptured marked individuals, avoiding the challenges associated with estimating movement from parasitized hosts. All parasitoids moved farther than their host (Jones et al., 1996). Small-scale studies can provide key insights into local population dynamics, but may be less relevant to colonization processes that involve longer-distance movement events.

Few studies have examined the movement of prey relative to their predators at large spatial scales, despite calls for increased research in this area (Cronin and Reeve, 2005). In a seminal study, Cronin et al. (2000) quantified the long-distance dispersal of the beetle Thanasimus dubius, an important predator of the southern pine beetle, Dendroctonus frontalis. Using mark-release-recapture data fit with a heterogeneous diffusion model, Cronin et al. (2000) estimated that the radius containing 95% of dispersing T. dubius individuals was 5.1 km. They compared the pattern and range of movement of the predator to that of D. frontalis, whose 95% radius was estimated in Turchin and Thoeny (1993) to be 2.3 km, and concluded that predators were dispersing farther than their prey. Cronin et al. (2000) used estimated differences in the dispersal ability of the predator and its prey to address the formation of discrete D. frontalis infestations in a homogeneous landscape, as modeled by Mimura and Murray (1978). Just as Cronin et al. (2000) used their experimental results to inform theory, the biological control theoretical literature can be enriched with knowledge of relative dispersal abilities. As an example, optimal farmscape design of annual agroecosystems to enhance biological control would differ depending on the relative dispersal abilities of pests and their natural enemies. If pests routinely out-disperse their natural enemies, then strategies that enhance colonization of natural enemies (including augmentative releases, intercropping, etc.) will be important. Alternatively, if natural enemies out-disperse their prey, then different strategies, including potentially clumping of fields of a particular crop to create huge monocultures, may reduce pest densities (Segoli and Rosenheim, 2012).

In determining what species will be an effective predator, it is important to consider not only a predator's dispersal ability, but also its trophic strategy. For specialist predators, it seems reasonable to suggest that the most effective predators would be those that demonstrate similar dispersal ability to their prey, as this would avoid both of two adverse scenarios: (i) the prey out-disperses its predators and thus escapes from control, and (ii) the predator out-disperses its prey, and as a result lacks the food resources needed to sustain its population. The idea that specialist predators have dispersal abilities similar to those of their prey has been suggested in discussions of specialist species' responses

to climate change (Berg et al., 2010). Generalist predators may be successful as early colonists, even if they out-disperse one of their prey species, because they may be able to subsist on alternate prey and build up large populations that subsequently suppress laterdeveloping pest populations (Settle et al., 1996). We hypothesize that omnivorous predators, which can sustain their populations using plant-based resources, may have the largest advantage of all in temporary agroecosystems, as they may be able to sustain themselves when their prey are rare or completely absent, i.e. during the establishment of a new crop. C. carnea (Limburg and Rosenheim, 2001), H. convergens (Pemberton and Vandenberg, 1993), Nabis spp. (Stoner, 1972), and G. punctipes (Stoner, 1970) all use food resources provided by the cotton plant, feeding on extrafloral nectar and, in some cases, directly on plant tissues. In the absence of prey, plant resources increased the longevity of these predators. To our knowledge, these hypotheses linking trophic strategy to the evolution of dispersal behaviors have yet to be investigated formally.

The relative scale of Lygus movement found in our study, MDF = 1157 m, supports the inferences made by Carrière et al. (2006) who suggested that source populations up to 1500 m away have the potential to affect the population density of Lygus in a focal cotton field. Our results suggest that Lygus' dispersal ability is much greater than estimated by Bancroft (2005). Bancroft (2005) examined the movement of Lygus using a traditional markrelease-recapture study in a small field plot (samples were taken at distances up to 30 m away from a central release point) and found the mean dispersal distance to be 4.6 m/day, with 98% of the population dispersing less than 15.6 m/day in cotton, based on diffusion estimates. The difference in scale of investigation is likely the reason behind the differing conclusions with regards to Lygus' dispersal ability. Dispersal estimates in that study may have been lower because marked individuals were released in the middle of alfalfa and cotton fields that consisted of mature stands of vigorous host plants, habitats that are considered suitable for Lygus feeding and reproduction. In contrast, in our study, the host crop was harvested, and Lygus seeking feeding opportunities were forced to leave the field, potentially promoting longer distance movement. Schellhorn et al. (2008) also observed accelerated colonization rates by male Diadegma semiclausum parasitoids following plowing, as compared to movement behavior in undisturbed habitats.

Our study is limited by several issues common to large-scale experiments. Foremost among these is a lack of replication. Our objective in this study was to describe the colonization processes for mobile insects in large-scale commercial agriculture, implying that we needed to work at a large spatial scale. We conducted our experiments over three years in commercial farms where we had no control over the configuration of fields. As a result, the scale and sampling design of each experiment varied, and we were unable to make formal comparisons across years. Additionally, most of our sampling in cotton occurred in a single direction, preventing us from exploring hypotheses related to directional dispersal or the effects of the predominant wind direction. Despite these shortcomings, we suggest that the general insight gained from our study, that our focal pest species exhibited intermediate mean dispersal distances compared to its suite of generalist predators, will add to knowledge of spatial predator-prey interactions and biological control. Indeed, this general result reinforces the view emerging from recent studies of dispersal by parasitoids and their hosts (Elzinga et al., 2007; van Nouhuys and Hanski, 2002). Finally, as in most long-distance dispersal studies, our study suffers from small recapture sample sizes. These recapture rates would likely be improved if we used traps baited with semiochemicals (as in Cronin et al., 2000), but these have yet to be developed in our system. Alternatively, successful dispersal studies often recapture individuals in specialized habitats, as in the aquatic mesocosms used by

Hein and Gillooly (2011), but this is difficult to do in our system when working with generalist species.

5. Conclusions

The primary result of our study is that a harvest-triggered longdistance dispersal event, which is a central feature of ephemeral agroecosystems, did not result in *Lygus* out-dispersing its complex of generalist predators. This suggests that limited predator dispersal is not the primary mechanism explaining why *Lygus* is under poor biological control. *Lygus* is a key pest in cotton and other crops, and further work must be done to understand the population dynamics and dispersal of this important generalist pest. Our understanding of relative movement would be enriched by a larger data set that could fully characterize the dispersal curves for the predators and their prey. Additionally, it will be important to determine how the relative dispersal abilities of predators and prey might vary in heterogeneous instead of homogeneous patch types.

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Appendix A. Supplementary data

Supplementary data associated with this article can be found, in the online version, at http://dx.doi.org/10.1016/j.biocontrol.2012. 09.008.

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